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## Rotational Motion Answers

Newton's 2nd law for linear motion. Here, the moment of inertia  $I$  plays the same role as the object's mass in  $F = ma$ . It tells us how difficult is to set an object in rotational motion. In the figure below, the two cylinders have the same masses. However, the

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PDF Chapter 8- Rotational Motion - University of Regina. Rotational Dynamics; Torque Equation 8-25 is the rotational equivalent of Newton's 2nd law for linear motion. Here, the moment of inertia  $I$  plays the same role as the object's mass in  $F = ma$ . It tells us how difficult is to set an object in rotational motion.

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Newton's second law for rotational motion is:  $\Sigma \tau = I\alpha$  (8.8) where  $\Sigma \tau$  is the sum of all torques acting on the rigid body,  $\alpha$  is the angular acceleration and  $I$  is the moment of inertia. Normally the mass is the easy part. With rotational motion, the 'mass' part is the moment of inertia.

### Chapter 8 Rotational Motion - Physics

Chapter 8 Rotational Motion Review Questions Circular Motion 1. What is meant by tangential speed? 2. Distinguish between tangential speed and rotational speed. Tangential speed is as stated in the previous answer, while rotational speed is the number of rotations per unit of time.

### Chapter 8 Rotational Motion - Review Questions ...

Chapter(8 Rotational(Motion.

Centripetal\*Acceleration\*and\*Tangential\*Acceleration  $a_c = v^2 / r$   
 $a_t = r \alpha$

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## Chapter 8

AP Physics Study Guide Chapter 8 & 9: Rotational Velocity  
Angular quantities ( " ! "# \$ = !! (" != 2! ("  
Degree to radians:  $32.58 = ! ! "# $ "$  One radian =  $57.3 ("$   
Angular velocity (

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A clockwise rotation indicates a negative torque while a counterclockwise torque acts in the positive direction. If two or more torques are present on an object at rest they are added together, and if the net torque is not 0 the object will begin to rotate.

## Chapter 8: Rotational Equilibrium and Rotational Dynamics ...

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Since the rotational inertia is a sum, you can always mentally decompose the object into several parts, find the rotational inertia of each part, and then add them. The rotational inertia depends on the location of the rotation axis. The same object will have a different rotational inertia depending on where it is rotating.

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